### Outlier Detection with Dirichlet Process Mixtures

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### Dirichlet Process Mixture (DPM)

$$\begin{array}{rcl} y_i | \theta_i & \sim & L(\theta_i; y_i) & i = 1 \dots n \\ \theta_i & \sim & G \\ G & \sim & DP(\alpha, G_0) \end{array}$$

- ► *DP* is a distribution over distributions
- G is discrete  $\Rightarrow P(\theta_j = \theta_k) > 0$
- if  $\theta_j = \theta_k$ , then  $y_j$  and  $y_k$  are clustered



## Product Partition Model (PPM)

$$\begin{array}{rcl} y_i | z_i = k, \phi_k & \sim & L(\phi_k; y_i) & i = 1 \dots n \\ \phi_k & \sim & G_0(\phi_k) & k = 1 \dots r \\ P(\boldsymbol{z}) & \propto & \prod_{k=1}^r \alpha \Gamma(n_k) \end{array}$$

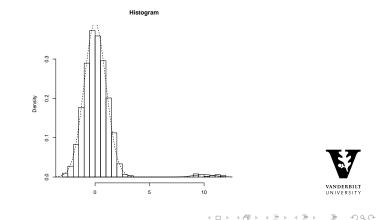
- ► z is the *data partition* parameter
- estimating z 'partitions', or 'clusters' the data
- if  $z_j = z_k$ , then  $y_j$  and  $y_k$  are clustered
- ▶ [Hartigan, 1990]



## Outlier Detection Using Partitioning

Steps:

- 1. set a "small" cluster threshold (e.g. 1% of n)
- 2. estimate the data partition (*i.e.* cluster the data)
- 3. "small" clusters are considered outlying
- ► an outlier partition contains one or more small outlier clusters



If the data partition (z) is estimated, and outlier clusters are discovered, how much evidence suggests that these clusters are truely different from the others?

Can the partition estimate be restricted such that a minimum level of evidence is required to identify outlier clusters? Yes!



### A Criterion for Outlier Detection: Setup

Consider an outlier partition  $z_o$  (n = 10):

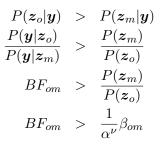
$$\begin{aligned} \boldsymbol{z}_{o} &= [1, 1, 1, 1, 1, 1, 1, 1, 2, 3] \\ \boldsymbol{z}_{m1} &= [1, 1, 1, 1, 1, 1, 1, 1, 1, 3] \\ \boldsymbol{z}_{m2} &= [1, 1, 1, 1, 1, 1, 1, 1, 2, 1] \\ \boldsymbol{z}_{m3} &= [1, 1, 1, 1, 1, 1, 1, 1, 2, 2] \\ \boldsymbol{z}_{m4} &= [1, 1, 1, 1, 1, 1, 1, 1, 1, 1] \end{aligned}$$

- $z_{m}$  are formed by merging the outliers in  $z_{o}$ .
- ▶ outlier detection is a decision between  $z_o$  and  $z_m$ ..
- denote the collection  $\boldsymbol{z}_{m}$ . as  $M_o$



A Criterion for Outlier Detection: The Trick

 $oldsymbol{z}_o$  is favored if, for all  $oldsymbol{z}_m \in M_o$ 



- $\blacktriangleright~\nu$  is the number of clusters merged to arrive at  $\boldsymbol{z}_m$
- $\beta_{om}$  (a ratio involving  $\Gamma(\cdot)$ ) is always  $\geq 1$  for  $\boldsymbol{z}_m \in M_o$
- to favor  $\boldsymbol{z}_o$ ,  $BF_{om}$  must exceed  $\frac{1}{\alpha^{\nu}}$
- $BF_{om}$  must increase  $1/\alpha$  fold for each outlier



## A Criterion for Outlier Detection: How to Fix $\alpha$

- $\blacktriangleright$  set the criteria by fixing  $\alpha$
- ► use Jeffrey's scale of evidence for Bayes factors
- ► [Efron and Gous, 2001]

Evidence for  $z_o$ 

- 1/lpha~<1 negative
- $1 \leq 1/lpha < 3$  barely worth a mention
- $3 \leq 1/lpha < 20$  positive
- $20 \leq -1/\alpha \quad < 150 \quad {\rm strong}$
- $150 \leq 1/lpha$  very strong



## A Criterion for Outlier Detection: Nice Properties

MAP partition estimates automatically satisfy the criterion for fixed  $\alpha$ . Hence, no special or novel computational methods are required.

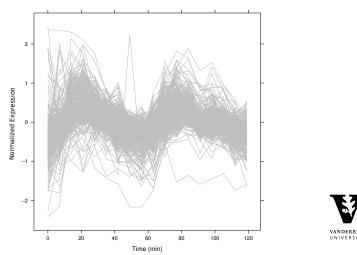
Because the DPM accommodates any data likelihood, outlier detection with Dirichlet process mixtures is possible with any statistical model that specifies a likelihood function.

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## Microarray Time Series in Cell Cycle Synchronized Yeast

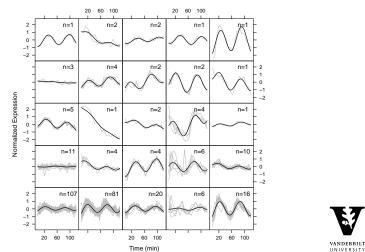
G1 Phase

- ▶ [Spellman et al., 1998]
- ▶ 66 minute period, 2 cycles



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# Microarray Time Series in Cell Cycle Synchronized Yeast $\alpha = \frac{1}{150}$



G1 Phase

## MAP Estimation for z

- ► Agglomeration [Ward, 1963]
- ► Polya Urn Gibbs Sampler [MacEachern, 1994]
- ► Split-Merge Sampler [Jain and Neal, 2004]
- ► SUGS [Wang and Dunson, 2010]
- sampling is overkill for MAP estimation
- we proposed a stochastic algorithm:
  - consists of 'Explode' and 'Merge' steps
  - consistent for the MAP estimate
  - avoids complexity of sampling
  - facilitates parallel search of partition space
- ► R package profdpm



## Outlier Detection with Finite Mixtures

- ► [Fraley and Raftery, 2002]
- select z that maximizes the BIC
- requires  $BF_{om} > n^{\frac{\rho}{2}\nu}$
- ► *i.e.*  $BF_{om}$  must increase  $n^{\frac{\rho}{2}}$  fold for each outlier
- ► DPM outlier detection is generally more conservative.





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